Region Visualization
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Image segmentation and region identification is an important part of most computer vision applications. Several VisionX tools are available to simplify the visualization process.

The visualization issue is illustrated in the binary image above; the outcome of a segmentation is a binary image. Displaying just that image, in general, provides limited useful information.

See slide 3 for best methods.

Region Visualization: Images
Task: to visualize and compare two different segmentations

Original Image: car.vx
Segmentation A: carA.vx
Segmentation B: carB.vx

Region Visualization: Best methods region
Task: to visualize a single segmentation
In general the best method is to add to the grey level image

%vrdiff carA.vx carB.vx –cs of= | vccvt –i | vcmod ig=car.vx of=carVCx.vx

Dynamic intensity mapping may be better for images with high dynamic range

%vrdiff carA.vx carB.vx –cs of= | vccvt –i | vcmod –d ig=car.vx of=carVCy.vx

A simple color index image may be generated by vrdiff

%vrdiff carA.vx CarB.vx ig=car.vx –ci of=carVCr.vx

Region Visualization: Region comparison
Task: to quantitatively compare two different segmentations

%vrdiff carA.vx CarB.vx -sh apcnt=13145; bpcnt=14165; overlap=12061; anotb=1084; bnota=2104; union=15249; diff=3188; tp=12061; tn=12011; fp=1084; fn=2104; fpc=0.7749; sim=0.79093; sens=0.851464; spec=0.917220; dsc=0.883266;

Vrdiff: provides both a quantitative analysis of the two binary images and various visualizations.

For the analysis shown on the left see the crdiff man page. Be sure that the metric you use is the correct one for the application.

Region Visualization: single region
Task: to visualize a single segmentation
In general the best method is to add to the grey level image

%vrdiff carA.wx CarA.wx ig=car.wx –ci of=carVCr.wx

In some cases an outline may be better.

%vmpix car.wx CarA.wx | vcmix car.wx of=carV2.wx

On overlay is possible but other methods are better.

%vcmix car.wx CarA.wx of=carV1.wx
Region Visualization: single region (no color)

Task: to visualize a single segmentation

If color is not available then an outline may be best.

%vmpix if=carA.vx of=tmp
%vcmix ig=tmp carA.vx of=carVg2.vx -g

In some cases, especially in the case of many small regions an overlay may be better.

%vmpix carA.vx | vcmix carA.vx of=carVg2.vx

* Vcmix cannot accept a pipe to its if= input.

Region Visualization: single region (color image)

Task: to visualize a single segmentation

If the original image is already in color then covert to gray first in order to allow regions

%vchan -c if=carA.vx of=carA.vx
%vrdiff carA.vx carB.vx of= | vccvt -i | vcmod ig=carA.vx of=carVCx.vx

And for a single region just repeat the name

%vrdiff carA.vx carA.vx -cs of= | vccvt -i | vcmod ig=carA.vx of=carVCx.vx

Presenting the original image next to the segment visualization is often a good idea.

Other Region Visualizations: color boundaries

Task: to visualize and compare two different segmentations

%vmpix if=carA.vx i2=carB.vx | vcmap ig=colormap.v4 of=carVC3.vx

%vmpix if=carA.vx i2=carB.vx | vcmix if=carA.vx of=carVg1.vx

Other Region Visualizations: grey options

Task: to visualize and compare two different segmentations

%vmpix if=carA.vx tf=0 | vrdiff if=carA.vx of=carVCg.vx

%vmpix if=carA.vx i2=carB.vx | vrdiff if=carA.vx of=carVCg.vx

Other Region Visualizations: other colors

Task: to visualize and compare two different segmentations

%vcmix carA.vx of=carVg1.vx -g

%vmpix if=carA.vx of=tmp
%vcmix ig=tmp carA.vx of=carVg2.vx -g

Region Visualization: Summary

- vrdiff is the key to good visualizations; see slide 3 for the best methods
- vcmod may be used with vrdiff to provide high quality true color visualizations; vcmod also can manage non-byte images and images with large dynamic ranges
- Many alternative methods for region visualizations are possible and may be appropriate in special situations
- vrdiff may also provide a quantitative comparative analysis of regions